(+1)-xxxxx-xx6x kx-x(at)gmail{dot}com

Suryansh Kumar

Assistant Professor, Texas A&M University

LinkedIn Website

Visual and Spatial Al

Visual Representation and Geometry

3D Acquisition and Generation

Robotics and Automation

Highlight. Texas A&M Seed Grant, Google Focused Research Grant, 6 top-tier computer science journal and 25+ peer-reviewed top-tier computer science conference publications, Best Algorithm Award from Disney Research at CVPR 2017, Nominated for Best Ph.D. Thesis 2019 at the Australian National University (ANU), ANU-HDR Merit Scholarship Award—funded by the Australian Research Council.

EDUCATION

Doctor of Philosophy (Ph.D.), Engineering and Computer Science, Australian National University **Master of Science (MS), Computer Science and Engineering,** IIIT-Hyderabad

Awarded: Dec. 2019 Awarded: July 2013

ACADEMIC APPOINTMENTS

Texas A&M University, College Station, Assistant Professor Visual Computing and Immersive Media, School of PVFA

Nov. 2023—Till Date

College Station, Texas, USA

Director of Visual and Continuous

• Director of Visual and Spatial AI Lab.

• Faculty Member of Virtual Production Institute, Fort Worth Texas.

ETH Zürich, Professorship and Post-Doctoral Researcher

Nov. 2019 — Oct. 2023

Computer Vision Lab (CVL), D-ITET, Appointed by: Luc Van Gool

• 3D Computer Vision, Deep Learning and Robotics.

Zürich, Switzerland

• Supervise Ph.D. thesis, MS thesis and Bachelor projects.

IIIT-Hyderabad, Research Assistant

Robotics Research Center (RRC), CSE

Jan. 2011 — Jul. 2013

Work on robot vision problems and assist lab.

• Visual exploration and path planning for indoor mobile robots.

Hyderabad, India

INDUSTRIAL APPOINTMENTS

Google Research, New York

May 2019 — Aug. 2019

· Geometric AI, Geometry Processing

· Dense shape matching

Uurmi Systems now Mathworks India

May 2014 — Aug. 2015

· Computer Vision, Image Enhancement, and Robotics

· Visual Tracking, Segmentation, Structure from Motion

INRIA Grenoble (e-Motion Group), Visiting Scientist

Aug. 2013 — Feb. 2014

· Autonomous Driving, Computer Vision

State Estimation, Path Planning, Inverse Reinforcement Learning, Robotics

TEACHING

Delivered over \$1000K+ in instructional services. Prepared course material, student grading, supervision and feedback.

Lecture on 3D Vision in Image Analysis and Computer Vision Course
Teaching Assistant for Computer Vision Course (ENGN4528/6528)
Teaching Assistant for Computer Vision Course (ENGN4528/6528)
Teaching Assistant for Individual Engineering Project Course (ENGN4200)

ETH Zürich, Fall 2022 ANU, Feb. 2018-Jul. 2018 ANU, Feb. 2017-Jul. 2017 ANU, Feb. 2017-Jul. 2017

COMPUTING SKILLS

Programming Language: C/C++, Python. Scripting Language: Matlab, Octave, Unix Shell Programming Libraries and APIs: OpenCV, OpenGL, Open3D, ROS, Eigen, STL, Numpy, Scipy, Pangolin. Deep Neural Network Framework: PyTorch, PyTorch3D. Web and Documentation: HTML, CSS, ET_FX. Others: Embedded C, Unix System Programming.

INTERNATIONAL ACADEMIC SERVICE

Reviewer: IEEE Transactions on Pattern Analysis and Machine Intelligence (T-PAMI), Conference on Computer Vision and Pattern Recognition (CVPR), International Conference on Learning Representations (ICLR), International Conference on Computer Vision (ICCV), European Conference on Computer Vision (ECCV), International Conference on Robotics and Automation (ICRA), Robotics and Automation Letter (RAL), Conference on 3D Vision (3DV), International Journal on Computer Vision (IJCV).